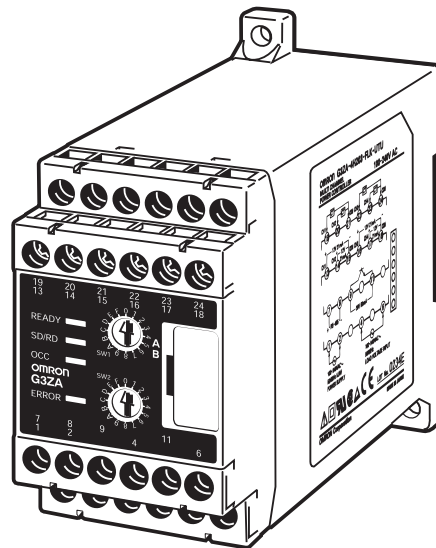


G3ZA Multi-channel Power Controller

User's Manual



G3ZA

Multi-channel Power Controller

User's Manual

Produced April 2004

Preface

OMRON products are manufactured for use according to proper procedures by a qualified operator and only for the purposes described in this manual.

This manual describes the functions, performance, and application methods needed for optimum use of the G3ZA.

Please observe the following items when using the G3ZA.

- This product is designed for use by qualified personnel with a knowledge of electrical systems.
- Read this manual carefully and make sure you understand it well to ensure that you are using the G3ZA correctly.
- Keep this manual in a safe location so that it is available for reference when required.

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Read and Understand this Manual

Please read and understand this manual before using the product. Please consult your OMRON representative if you have any questions or comments.

Warranty and Limitations of Liability

WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON. OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, REGARDING NON-INFRINGEMENT, MERCHANTABILITY, OR FITNESS FOR PARTICULAR PURPOSE OF THE PRODUCTS. ANY BUYER OR USER ACKNOWLEDGES THAT THE BUYER OR USER ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. OMRON DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED.

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OMRON SHALL NOT BE RESPONSIBLE FOR SPECIAL, INDIRECT, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED ON CONTRACT, WARRANTY, NEGLIGENCE, OR STRICT LIABILITY.

In no event shall the responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted.

IN NO EVENT SHALL OMRON BE RESPONSIBLE FOR WARRANTY, REPAIR, OR OTHER CLAIMS REGARDING THE PRODUCTS UNLESS OMRON'S ANALYSIS CONFIRMS THAT THE PRODUCTS WERE PROPERLY HANDLED, STORED, INSTALLED, AND MAINTAINED AND NOT SUBJECT TO CONTAMINATION, ABUSE, MISUSE, OR INAPPROPRIATE MODIFICATION OR REPAIR.

Application Considerations

SUITABILITY FOR USE

OMRON shall not be responsible for conformity with any standards, codes, or regulations that apply to the combination of products in the customer's application or use of the products.

At the customer's request, OMRON will provide applicable third party certification documents identifying ratings and limitations of use that apply to the products. This information by itself is not sufficient for a complete determination of the suitability of the products in combination with the end product, machine, system, or other application or use.

The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products.

- Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this manual.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
- Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

PROGRAMMABLE PRODUCTS

OMRON shall not be responsible for the user's programming of a programmable product, or any consequence thereof.

Disclaimers

CHANGE IN SPECIFICATIONS

Product specifications and accessories may be changed at any time based on improvements and other reasons.

It is our practice to change model numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the products may be changed without any notice. When in doubt, special model numbers may be assigned to fix or establish key specifications for your application on your request. Please consult with your OMRON representative at any time to confirm actual specifications of purchased products.

DIMENSIONS AND WEIGHTS

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

PERFORMANCE DATA

Performance data given in this manual is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

ERRORS AND OMISSIONS

The information in this document has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.



Safety Precautions

■ Definition of Precautionary Information





The following notation is used in this manual to provide precautions required to ensure safe usage of the product.

The safety precautions that are provided are extremely important to safety. Always read and heed the information provided in all safety precautions.






The following notation is used.

 WARNING	<p>Indicates a potentially hazardous situation which, if not avoided, will result in minor or moderate injury, or may result in serious injury or death. Additionally there may be significant property damage.</p>
 CAUTION	<p>Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or in property damage.</p>

■ Symbols

Symbol		Meaning
Caution		General Caution Indicates non-specific general cautions, warnings, and dangers.
		Electrical Shock Caution Indicates possibility of electric shock under specific conditions.
Prohibition		General Prohibition Indicates non-specific general prohibitions.
Mandatory Caution		General Caution Indicates non-specific general cautions, warnings, and dangers.

■ Precautions

 WARNING	
Do not touch the terminals and the wires while power is being supplied. Doing so may possibly result in electric shock. Make sure that the terminal cover is installed before using the product.	
 CAUTION	
Do not allow pieces of metal, wire clippings, or fine metallic chips or filings from installation to enter the product. Doing so may occasionally result in electric shock, fire, or malfunction.	
Do not use the product in locations of flammable or explosive gases. Doing so may occasionally result in minor or moderate explosion, causing minor or moderate injury, or property damage.	
Do not attempt to disassemble, repair, or modify the product. Doing so may occasionally result in minor or moderate injury due to electric shock.	
Perform correct setting of the product according to the application. Failure to do so may occasionally cause unexpected operation, resulting in minor or moderate injury, or damage to the equipment.	
Ensure safety in the event of product failure by taking safety measures, such as installing a separate monitoring system to provide alarms for preventing excessive temperature rise. Product failure may occasionally prevent control operation, resulting in damage to the connected facilities and equipment.	
Tighten the terminal screws securely using a tightening torque within the following ranges. Loose screws may occasionally cause fire, resulting in minor or moderate injury, or damage to the equipment. Terminal screws: 0.40 to 0.56 N·m	

Precautions for Safe Use

- (1) Do not use the product in the following locations.
 - Locations subject to direct radiant heat from heating equipment
 - Locations where the product may come into contact with water or oil
 - Locations subject to direct sunlight
 - Locations where dust or corrosive gases (in particular, sulfuric or ammonia gas) are present
 - Locations subject to extreme temperature changes
 - Locations where icing or condensation may occur
 - Locations subject to excessive shocks or vibration
- (2) Use this product within the rated load and power supply.
- (3) Ensure that the rated voltage is achieved no longer than 2 s after turning the power ON.
- (4) Use/store within the rated temperature and humidity ranges. Provide forced-cooling if required.
- (5) Minimum mounting distance of G3ZA is 10 mm.
When mounting the G3ZA near the SSRs, mount the G3ZA so as to not interfere with the heat dissipation of the SSR.
- (6) Use the specified size of insulated type crimp terminals (M3, width: 5.8 mm max.) for wiring and attach insulative sleeves. To connect bare wires, use AWG22 (cross section: 0.326 mm²) to AWG14 (cross section: 2.081 mm²) to wire the power supply terminals and AWG22 (cross section: 0.326 mm²) to AWG16 (cross section: 1.039 mm²) for other terminals.
- (7) Be sure to confirm the correct terminal and polarity when wiring the terminal block and connectors.
- (8) Do not connect any conductors to unused terminals.
- (9) In order to prevent inductive noise, wire the lines connected to the product separately from power lines carrying high voltages or currents. Do not wire in parallel with or in the same cable as power lines. Other measures for reducing noise include running lines along separate ducts and using shield lines.
- (10) Attach a surge suppressor or noise filter to peripheral devices that generate noise (in particular, motors, transformers, solenoids, magnetic coils or other equipment that have an inductance component).
Do not install the product near devices generating strong high-frequency fields or surges. When using a noise filter, check the voltage and current and install it as close to the product as possible.
- (11) For a safety disconnection of the power-line in the application the equipment shall be provided with disconnecting devices suitable for isolation.
(e.g. circuit breakers IEC60947-2, power switches IEC60947-3, power plugs etc.)
- (12) The G3ZA is for single-phase loads only. Connect only single-phase zero-cross SSRs.
Do not connect three-phase SSRs, magnetic relays, or SSRs that do not have zero-cross function.

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About this Manual:

This manual describes the installation and operation of the G3ZA Multi-channel Power Controller and includes the sections described below.

Please read this manual carefully and be sure you understand the information provided before attempting to install or operate the G3ZA. Be sure to read the precautions provided at the beginning of this manual.

The **Preface** provides precautions for using the G3ZA and information on using this manual.

Section 1 introduces the G3ZA and its features.

Section 2 describes preparations for using the G3ZA, including installation and wiring.

Section 3 describes application information, including settings, communications, and controlling operation.

Section 4 describes the functions of the G3ZA so that these functions can be used effectively according to the application.

Section 5 provides information on problems that may occur during operation and corrective measures.

The **Appendix** provides G3ZA specifications, tables of settings, and other information.



WARNING Failure to read and understand the information provided in this manual may result in personal injury or death, damage to the product, or product failure. Please read each section in its entirety and be sure you understand the information provided in the section and related sections before attempting any of the procedures or operations given.

SECTION 1
Overview

This section introduces the G3ZA and its features.

1-1	Features	2
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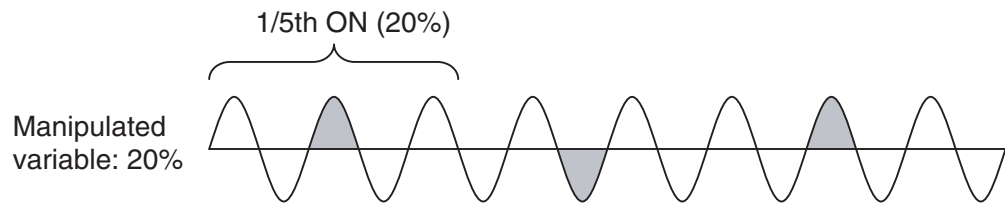
1-1 Features

The G3ZA is a Multi-channel Power Controller with externally connected SSRs. It can receive manipulated variables from a PLC or other host via RS-485 communications and control heater power with high precision via the SSRs.

Overview

Optimum Cycle Control

- Optimum cycle control is performed by driving SSRs according to load power detection and trigger signals. (Zero-cross SSRs are used.)
- Noise is suppressed while ensure high-speed response by turning outputs ON and OFF each half cycle to achieve high-precision temperature control.



Offset Control

- The timing of turning ON the control outputs for G3ZA channels can be offset.

Manipulated Value Calculations

- The manipulated variable can be calculated for one channel and the calculated value can be output for another channel.

Error Detection (4-channel Controllers Only)

- The current flowing through the heater can be monitored to detect heater burnouts, heater overcurrents, and SSR short circuits.

Number of Outputs Connected

- Between one and four outputs can be connected to 4-channel Controllers and between one and eight outputs can be connected to 8-channel Controllers.

Alarm Output

- An open-collector output terminal can be used to inform the host of errors without using communications.

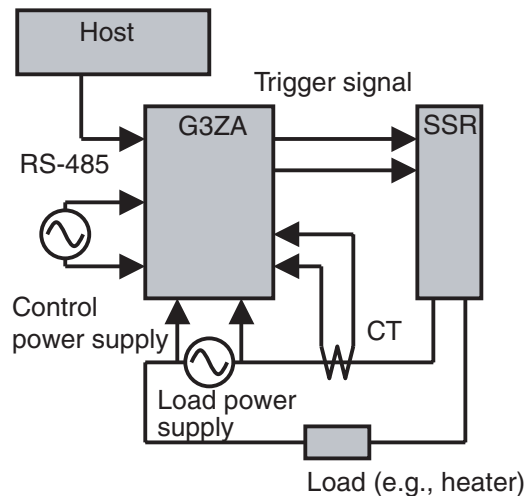
Installation

- RS-485 communications can be used to set and operate the G3ZA, reducing the amount of wiring required between the G3ZA and host.
- Up to 31 Controllers can be connected to one communications line. With 4-channel Controllers, up to 124 channels can be controlled, and with 8-channel Controllers, up to 248 channels can be controlled.

The following four models are available.

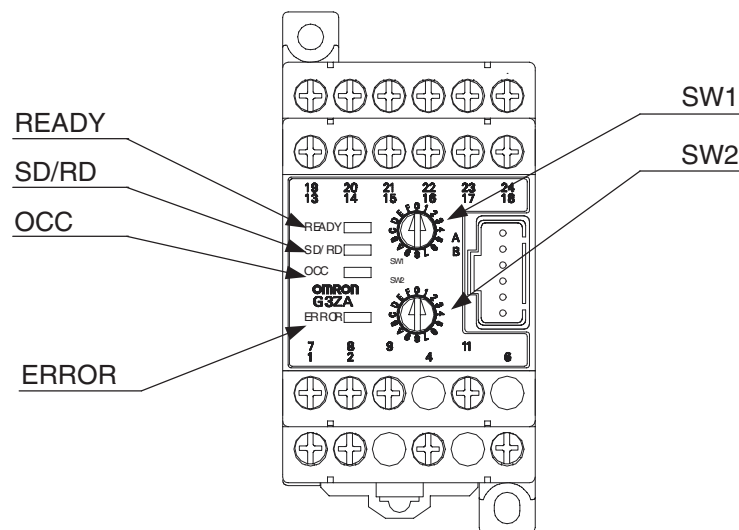
No. of channels	Error detection	Load power supply
4 channels	Supported	100 to 240 V
		400 to 480 V
8 channels	Not supported	100 to 240 V
		400 to 480 V

Connections



Note Connect a power supply with the same phase as the SSRs to the load power supply input terminals on the G3ZA.

Component Names and Functions



Operation Indicators

Operation indicator	Meaning
READY	Lit while power is being supplied.
SD/RD	Lit while communicating with the host.
OCC	Lit while a control output is ON.
ERROR	Lights or flashes when an error is detected.

Switches SW1 and SW2

SW1 and SW2 are used to set the communications unit number and baud rate. Refer to *3-1 Communications Settings* on page 14 for details.

SECTION 2

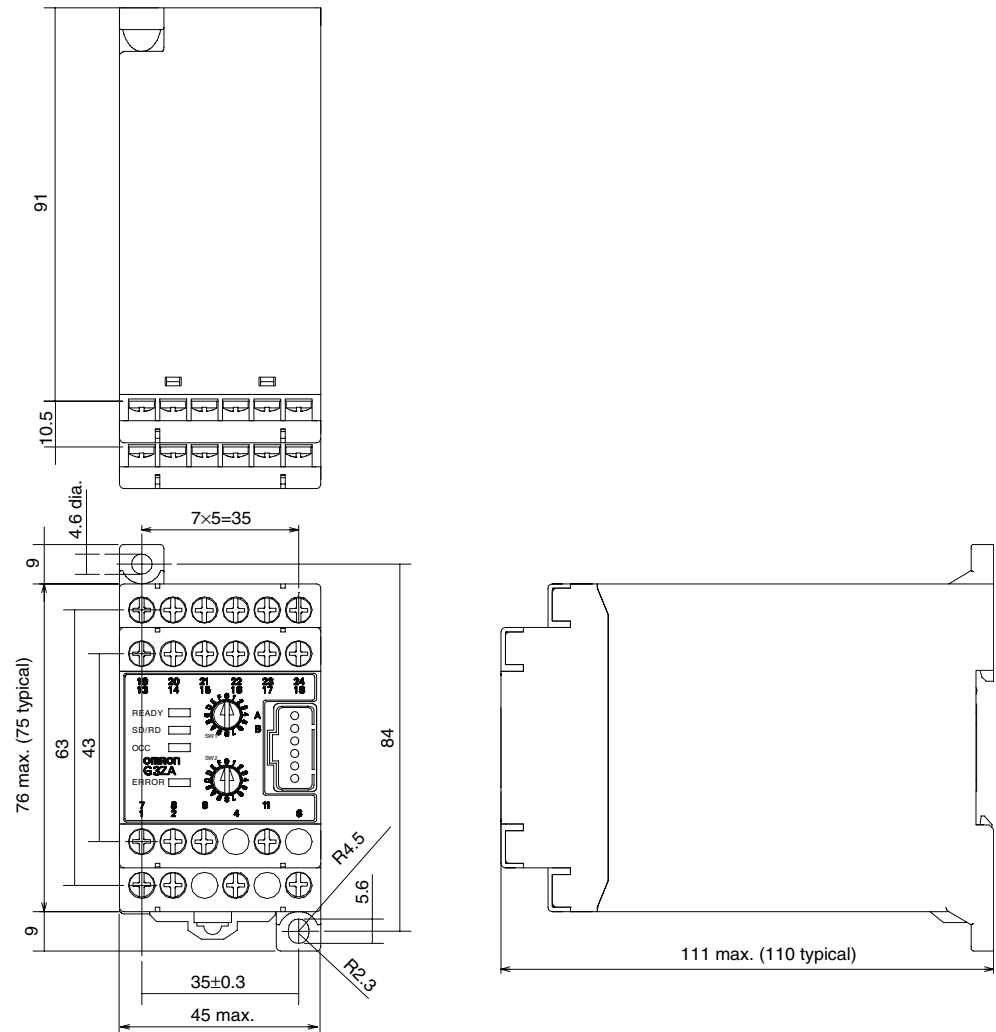
Preparations

This section describes preparations for using the G3ZA, including installation and wiring.

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2-1 Installation

Dimensions (Unit: mm)

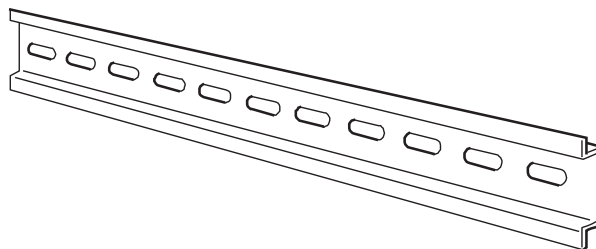


Mounting to DIN Track

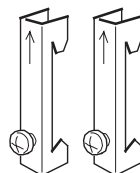
DIN Track Products

When installing a DIN Track inside a control panel, secure the DIN Track with screws in at least three locations.

- DIN Track: PFP-50N (50 cm) or PFP-100N (100 cm)

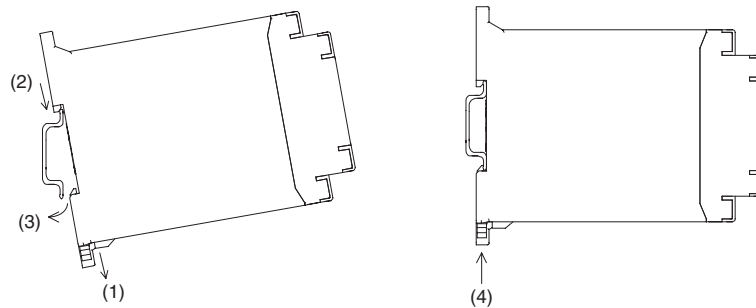


- End Plates: PFP-M

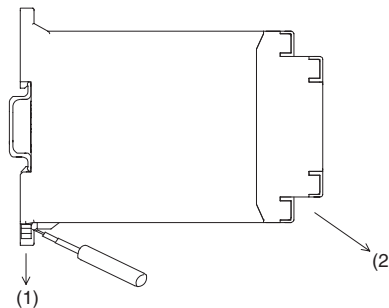


Mounting the G3ZA

Mount the G3ZA as shown in the diagram. First, pull down the DIN Track mounting hook (1) and hook the top of the G3ZA on the DIN Track (2). Then press the G3ZA onto the DIN Track far enough so that it can be locked in place (3) and push the DIN Track mounting hook up to lock the G3ZA in place (4).

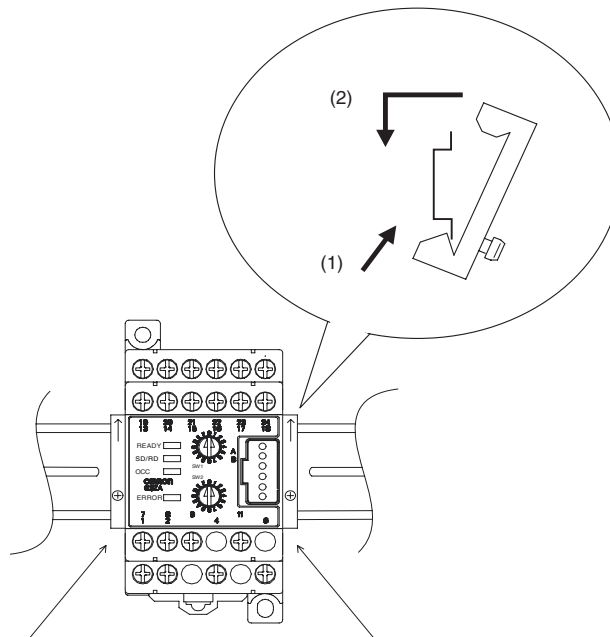
**Removing the G3ZA**

Use a flat-blade screwdriver to pull down the DIN Track mounting hook (1) and then pull out on the bottom of the G3ZA (2).

**Mounting End Plates**

Be sure to mount an End Plate on each side of the G3ZA so that it does not slide on the DIN Track.

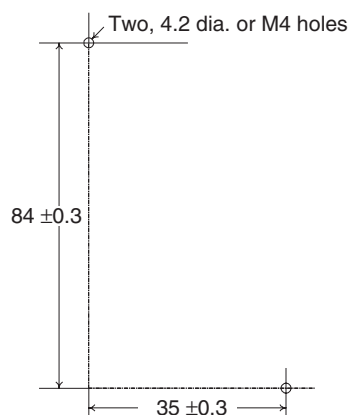
To mount an End Plate, hook the bottom of the End Plate on the bottom of the DIN Track (1), place the top of the End Plate on the DIN Track (2), and then pull down on the End Plate. Tighten the screw on the End Plate to secure it.



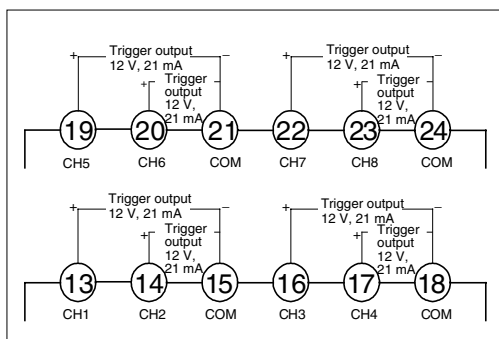
Note Always mount one End Plate on each side of the G3ZA.

Mounting the G3ZA with Screws

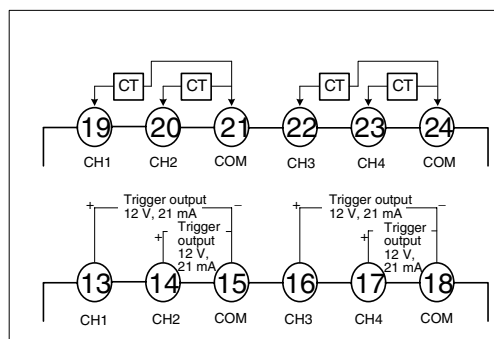
**Mounting Hole
Dimensions (Unit: mm)**



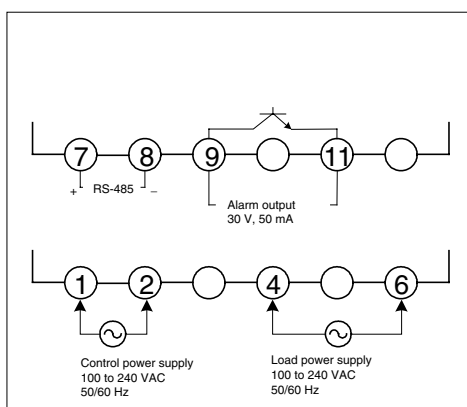
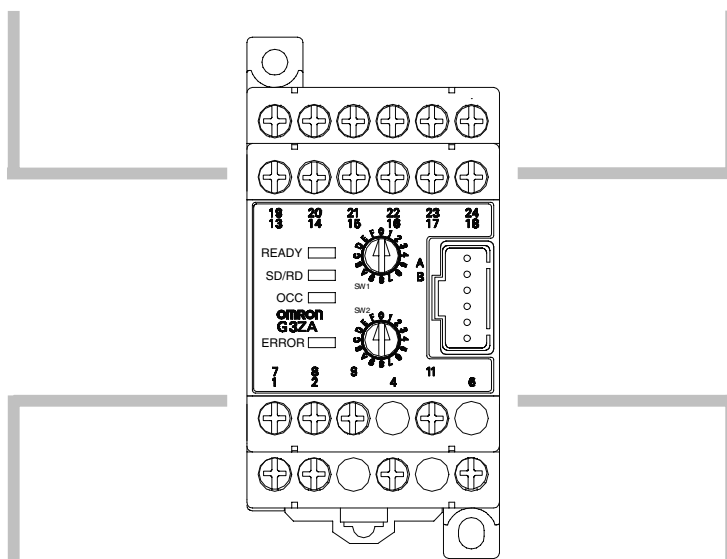
2-2 How To Use the Terminals



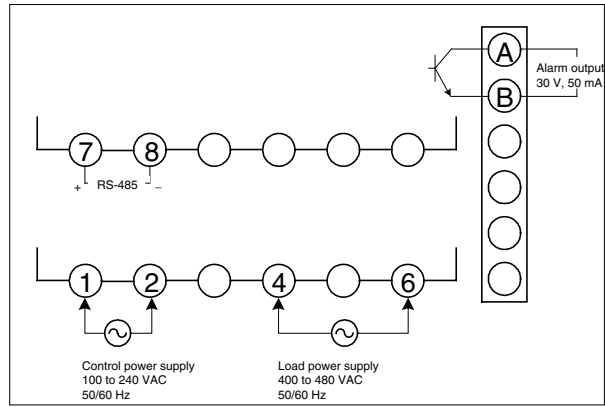
G3ZA-8A□03-FLK-UTU



G3ZA-4H□03-FLK-UTU



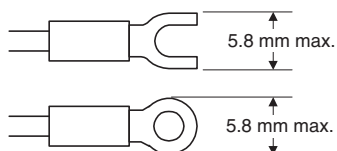
G3ZA-□□203-FLK-UTU



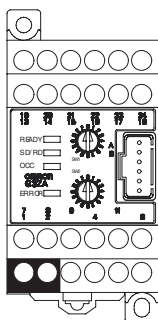
G3ZA-□□403-FLK-UTU

Wiring Diagrams

Use one of the following M3 solderless terminals for wiring.

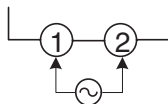


Use wires that are rated to withstand 70 °C minimum.

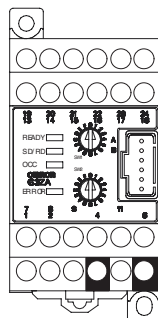
Controller Power Supply Terminals

In the wiring diagrams, the area within the lines indicating terminals numbers is inside the G3ZA and the area outside the lines are outside the G3ZA.

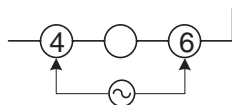
- Connect terminals 1 and 2 as follows:



- The input power is 100 to 240 VAC.

Load Power Supply Input Terminals

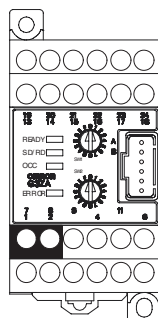
- To detect the zero-cross point of the load supply, connect the load power supply to terminals 4 and 6 as follows:



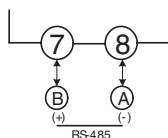
The voltage of the load power supply that can be connected depends on the model of the Controller.

100 to 240 VAC or 400 to 480 VAC

- The G3ZA detects the zero cross point of the load power supply.

Communications Terminals

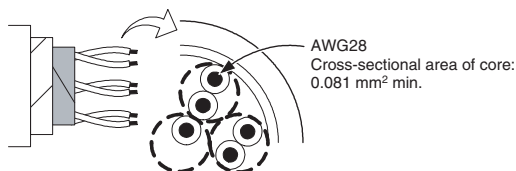
- To communicate with a host system, connect the communications line to terminals 7 and 8 as follows:



- The connection type can be 1: 1 or 1: N. For 1: N connections, up to 32 Units can be connected, including the host.
- The maximum cable length is 500 m total.

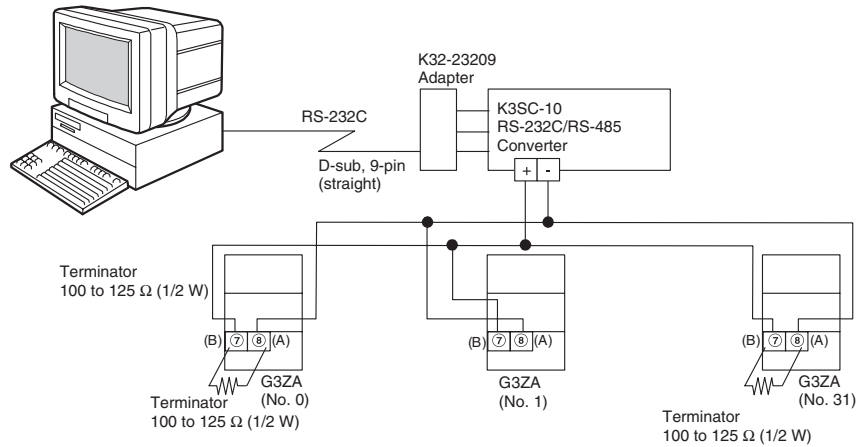
Cable Diagram (Reference)

- Use shielded twisted-pair cables (AWG28 to AWG16).

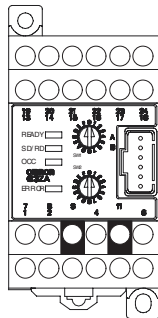


- A terminator must be connected to both ends of the communications path (including the PLC). Use a resistance of 100 to 125 Ω (1/2 W) in the terminators.
- Use an RS-232C/RS-485 converter to connect to a personal computer or other host with an RS-232C connection.

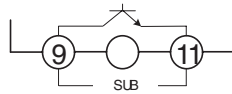
Converter: K3SC RS-232C/RS-485 Interface Converter



Alarm Output Terminals for the G3ZA-□□203-FLK-UTU

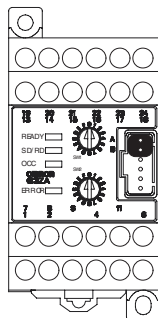


- Alarms are output on terminals 9 and 11.

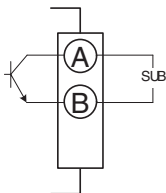


- The alarm output specifications are as follows:
Maximum load voltage: 30 VDC
Maximum load current: 50 mA
Maximum residual voltage: 1.5 V
Maximum leakage current: 1 mA

Alarm Output Terminals for the G3ZA-□□403-FLK-UTU

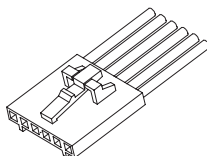


- Alarms are output on pins A and B of the connector.
- The alarm output specifications are as follows:



Maximum load voltage: 30 VDC
Maximum load current: 50 mA
Maximum residual voltage: 1.5 V
Maximum leakage current: 1 mA

- The C-Grid SL connector for Molex Incorporated can be used for the connector.

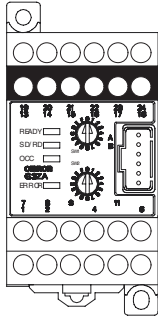


Model number: 51030-6030
C-Grid SL Housing

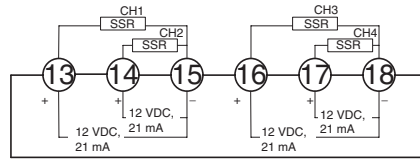
Model number: 52109-0660
C-Grid SL Housing/Press-fit Type

- The G3ZA-A300C Cable from OMRON also can be used.

Trigger Output Terminals



- The trigger outputs for channels 1 to 4 are output on terminals 13 to 18.



Output voltage: 12 VDC $\pm 15\%$

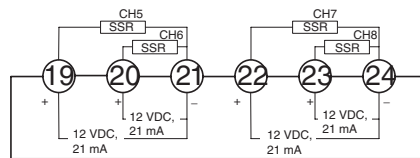
PNP

Maximum load current: 21 mA

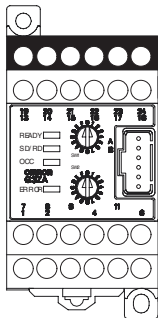
Short-circuit protection circuit provided.

Controllers without a Current Transformer Input Circuit (G3ZA-8A□03-FLK-UTU)

- The trigger outputs for channels 5 to 8 are output on terminals 19 to 24.

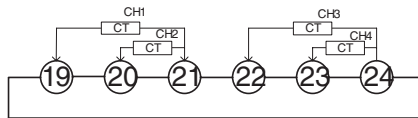


Current Transformer Input Terminals



Controllers with Built-in Current Transformer Circuits (G3ZA-4H□03-FLK-UTU)

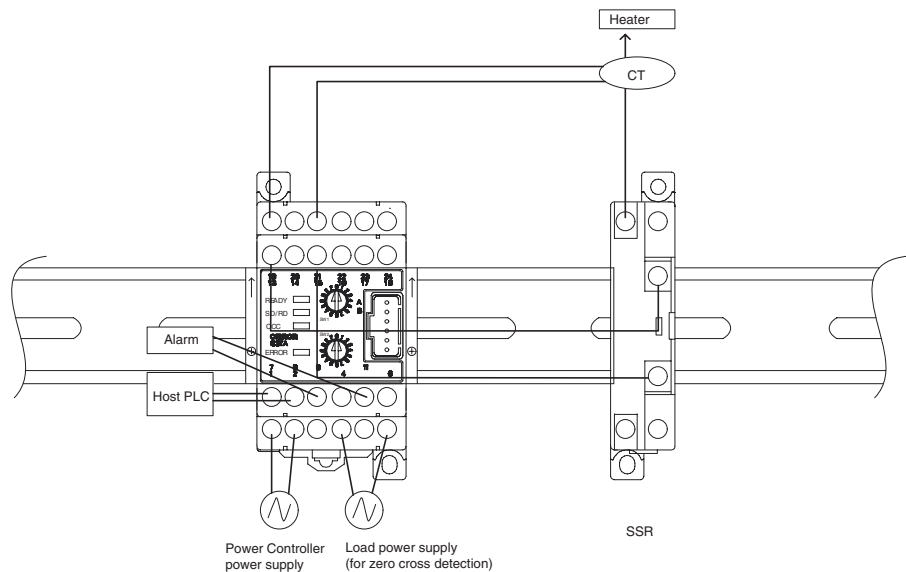
- Connect terminals 19 to 24 to the current transformers (no polarity) to detect heater burnouts, heater overcurrents, and SSR short circuits.



There are four current transformer inputs that can be used.

Use the E54-CT1 or the E54-CT3 from OMRON as the current transformer.

Wiring Example (G3ZA-4H□03-FLK-UTU)



SECTION 3

Using the G3ZA

This section describes application information, including settings, communications, and controlling operation.

3-1	Communications Settings	14
3-2	CompoWay/F Frame Structure	15
3-3	FINS-mini Text	17
3-4	Variable Area Write	17
3-5	Variable Area Read	18
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3-8	Controller Status Read	21
3-9	Echo-back Test	22

3-1 Communications Settings

G3ZA settings and operation are performed using RS-485 communications.

Communications Specifications

Transmission path connections	Multipoint
Communications method	RS-485
Sync method	Stop-start sync
Baud rate	9.6, 19.2, 38.4 or 57.6 kbit/s
Transmission code	ASCII
Data length	7 or 8 bits
Stop bits	1 or 2 bits
Error detection	Vertical priority: None, even, or odd
Flow control	None

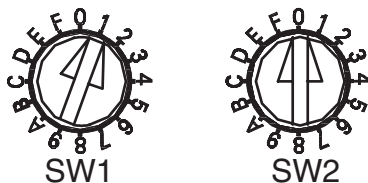
Communications settings are made as shown in the following table.

Setting	Setting range	Default	Setting method
Communications unit number	0 to 31	1	SW1
Baud rate	9.6, 19.2, 38.4 or 57.6 kbit/s	9.6 kbit/s	SW2
Data length	7 or 8 bits	7 bits	Communications
Stop bits	1 or 2 bits	2 bits	Communications
Parity	None, even, odd	Even	Communications
Send standby time	0 to 99 ms	20 ms	Communications

Setting the Communications Unit Number and Baud Rate

The communications unit number and baud rate are set first.

These settings are made with SW1 and SW2 on the front of the G3ZA.



SW1	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Unit number	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15

SW2	0	1	2	3
Baud rate (kbit/s)	9.6	19.2	38.4	57.6

- Note**
- (1) Refer to *Connecting More Than 16 Controllers* on page 38 in the *Appendix* when connecting more than 16 Controllers.
 - (2) The default settings are shaded in the above table.

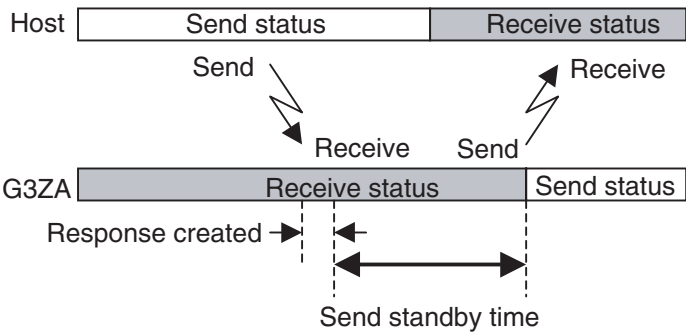
Other Communications Settings

Communications are used to set the data length, number of stop bits, parity, and send standby time. To change the settings, use communications with the default communications settings. Refer to *3-4 Variable Area Write* on page 17 for the procedure for changing these settings.

- Note**
- The settings will be enabled only when the power is turned ON again or the G3ZA is reset.

Send Standby Time

The send standby time is used to adjust the time required for the host to switch from sending to receiving status. For the G3ZA, this adjusts the time between creating a response after receiving a transmission and switching to send status.

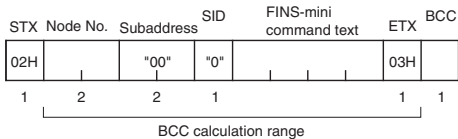


If switching time will not cause problems, the send standby time can be shortened to reduce the communications time with the host.

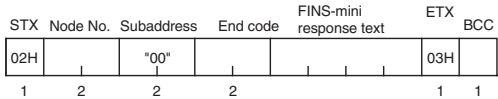
3-2 CompoWay/F Frame Structure

The propriety OMRON communications protocol called CompoWay/F is used as the communications protocol. Commands from the host and responses from the G3ZA are sent in data packets called frames. The structures of the command and response frames are shown below.

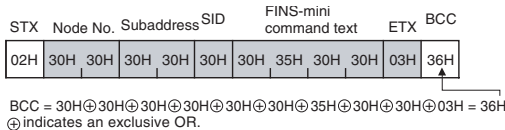
Command Frames



Response Frames



STX	Code that indicates the beginning of the communications frame. Always set 02H.
Node No.	This number specifies the destination. This is the same as the communications unit number set on SW1 and SW2.
Subaddress and SID	These are not used by the G3ZA. Set them to all zeros.
FINS-mini command text	The text of the command. Refer to 3-6 Operation Command on page 19 for details.
ETX	Code that indicates the end of the communications frame. Always set 03H.
BCC	This stores the result of the BCC calculation from the Node No. to EXT.



Using the G3ZA

End Codes (CompoWay/F Communications)

End code	Name	Description
"0F"	FINS command error	Could not execute the specified FINS command.
"10"	Parity error	Sum of bits that are "1" in received data does not agree with the set communications parity value.
"11"	Framing error	Stop bit is "0".
"12"	Overrun error	The next data was received when the received data buffer was full.
"13"	BCC error	Calculated BCC differs from received BCC.
"14"	Format error	Characters other than "0" to "9" or "A" to "F" in FINS-mini command text. (Refer to 3-9 <i>Echo-back Test</i> on page 22 for echo-back tests.)
"16"	Subaddress error	One or more of the subaddresses is missing.
"18"	Frame length error	The received frame exceeds the required number of bytes.
"00"	Normal end	Command was executed normally without error.

Data Type Notation

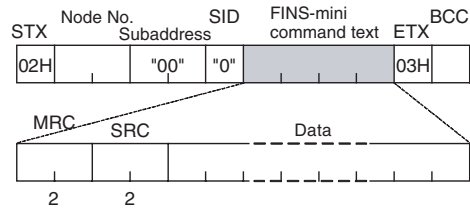
In this manual, hexadecimal and ASCII characters are expressed as shown in the following table.

Hexadecimal	An H is added to the end of the hexadecimal number. Example: 02H
ASCII characters	ASCII characters are given in quotation marks. Example: "00"

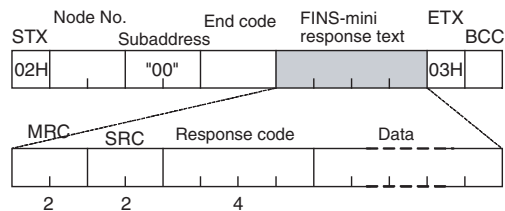
3-3 FINS-mini Text

The structure of FINS¹ command and response text is shown below.

Command Text



Response Text



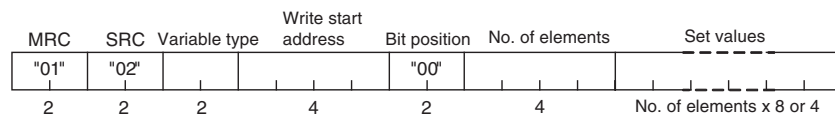
List of FINS-mini Service Commands

MRC	SRC	Service name	Description
"01"	"02"	Variable Area Write	Changes set values.
"01"	"01"	Variable Area Read	Reads set values.
"30"	"05"	Operation Command	Executes commands such as start/stop, manipulated variable save and software reset.
"05"	"03"	Controller Attribute Read	Reads the model number of the Controller.
"06"	"01"	Controller Status Read	Reads the operating status.
"08"	"01"	Echo-back Test	Performs an echo-back test.

3-4 Variable Area Write

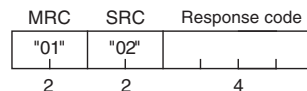
This command changes set values.

Command



Note The bit position is not used. Set it to "00".

Response



■ Variable Type and Write Start Address

Refer to the *Parameter Tables* on page 38 in the *Appendix*.

¹FINS: Short for Factory Interface Network Service.

The FINS protocol is used for message communications between controllers on OMRON FA networks.

■ Number of Elements

Specify the number of elements for which the set value is to be changed. Up to 8 elements can be specified.

■ Response Code

Response code	Error name	Cause
"1002"	Command length too short	The command is too short.
"1101"	Area type error	The specified variable type does not exist.
"1003"	Number of elements/Number of data do not agree	The specified number of elements does not agree with the actual number of data elements.
"1100"	Parameter error	The bit position specification is not "00". A set value is outside of the setting range.
"2203"	Operation error	An error occurred in nonvolatile memory.
"0000"	Normal end	Processing was completed normally.

Example: The following command changes the manipulated variable for channel 1 to 50% (set value: 8 digits).

Command: [STX]010000**102C10000000001000001F4**[ETX][BCC]

Response: [STX]010000**01020000**[ETX][BCC]

Example: The following command changes the manipulated variable for channel 1 to 50% (set value: 4 digits).

Command: [STX]010000**10281000000000101F4**[ETX][BCC]

Response: [STX]010000**01020000**[ETX][BCC]

3-5 Variable Area Read

This command reads set values.

Command

MRC	SRC	Variable type	Read start address	Bit position	No. of elements
"01"	"01"			"00"	
2	2	2	4	2	4

Note The bit position is not used. Set it to "00".

Response

MRC	SRC	Response code	Set values
"01"	"01"		
2	2	4	No. of elements x 8 or 4

■ Variable Type and Read Start Address

Refer to the *Parameter Tables* on page 38 in the *Appendix*.

■ Number of Elements

Specify the number of elements for which the set value is to be read. Up to 8 elements can be specified.

■ Response Code

Response code	Error name	Cause
"1001"	Command length too long	The command is too long.
"1002"	Command length too short	The command is too short.
"1101"	Area type error	The specified variable type does not exist.
"110B"	Response length too long	The number of elements is larger than the maximum number allowed.
"1100"	Parameter error	The bit position specification is not "00".
"2203"	Operation error	An error occurred in nonvolatile memory.
"0000"	Normal end	Processing was completed normally.

Example: The following command reads the control variable for channel 1 (set value: 8 digits).

Command: [STX]010000101C00001000001[ETX][BCC]

Response: [STX]0100000101000000000000[ETX][BCC]

Example: The following command reads the control variable for channel 1 (set value: 4 digits).

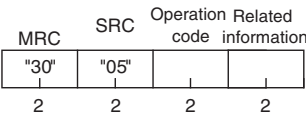
Command: [STX]010000101800001000001[ETX][BCC]

Response: [STX]010000010100000000[ETX][BCC]

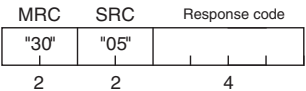
3-6 Operation Command

This command is used to start and stop operation, save the manipulated variable, execute a software reset, or initialize settings.

Command



Response



1. Operation Code and Related Information

Operation code	Description	Related information	Operation
"01"	Start/stop	Upper digit: Channel specification "0": Channel 1 "1": Channel 2 "2": Channel 3 "3": Channel 4 "4": Channel 5 "5": Channel 6 "6": Channel 7 "7": Channel 8 "F": All channels Lower digit: Start/stop "0": Start "1": Stop	Refer to 4-3 <i>Turning OFF the Control Output</i> on page 25.
"05"	Manipulated variable save	"00"	Refer to 4-1 <i>Changing the Manipulated Variable</i> on page 24.
"06"	Software reset	"00"	Performs the same processing as when the G3ZA is turned ON.
"0B"	Initialize settings	"00"	Refer to 5-2 <i>Handling Problems</i> .

Note There is no response for a software reset. Responses are returned for all other operation codes.

2. Response Codes

Response code	Error name	Cause
"1001"	Command length too long	The command is too long.
"1002"	Command length too short	The command is too short.
"1100"	Parameter error	The operation code or related information is not correct.
"2203"	Operation error	An error occurred in nonvolatile memory.
"0000"	Normal end	Processing was completed normally.

Example: The following command starts operation for channel 1.

Command: [STX]01000**30050100**[ETX][BCC]

Response: [STX]010000**30050000**[ETX][BCC]

3-7 Controller Attribute Read

This command reads the model number of the Controller and the communications buffer size.

Command

MRC	SRC
"05"	"03"
2	2

Response

MRC	SRC	Response code	Model number	Buffer size
"05"	"03"		"G3ZA-"	"00D9"
2	2	4	10	4

1. Model Number

G	3	Z	A	—	①	②	③	④	⑤
---	---	---	---	---	---	---	---	---	---

Number	Code	Meaning
①	"4"	4 channels
	"8"	8 channels
②	"H"	With current transformer input
	"A"	No current transformer input
③	"2"	Load power supply: 100 to 240 V
	"4"	Load power supply: 400 to 480 V
④⑤	"03"	RS-485

2. Buffer Size

The buffer size is 217 bytes (D9H).

3. Response Code

Response code	Error name	Cause
"1001"	Command length too long	The command is too long.
"2203"	Operation error	An error occurred in nonvolatile memory.
"0000"	Normal end	Processing was completed normally.

Example: The following command reads the model number and buffer size. The response shows the Controller has four channels, supports a current transformer, and has a load power supply of 400 to 480 V.

Command: [STX]010000**503**[ETX][BCC]

Response: [STX]010000**5030000G3ZA-4H40300D9**[ETX][BCC]

3-8 Controller Status Read

This command reads the operating status of the Controller.

Command

MRC	SRC
"06"	"01"
2	2

Response

MRC	SRC	Response code	Operating status	Related information
"06"	"01"			
2	2	4	2	2

1. Operating Status

Operating status	Meaning
"00"	The control output is ON for one or more channels.
"01"	The Controller is stopped or a zero cross error has occurred during operation.

2. Related Information

An OR of status bits 0 to 7 for all channels.

Refer to the *Status* in the *Parameter Tables* in the *Appendix*.

Note

To read the status of individual channels, use the Variable Area Read command for the desired channel. Refer to 3-5 *Variable Area Read* for details.

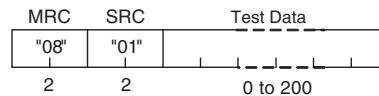
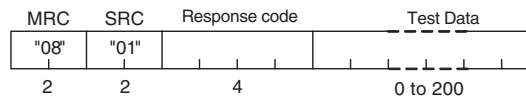
3. Response Code

Response code	Error name	Cause
"1001"	Command length too long	The command is too long.
"2203"	Operation error	An error occurred in nonvolatile memory.
"0000"	Normal end	Processing was completed normally.

Example:Command: [STX]010000**0601**[ETX][BCC]Response: [STX]010000**060100000100**[ETX][BCC]

3-9 Echo-back Test

This command performs an echo-back test.

Command**Response**

1. Test Data

Set the test data within the following ranges according to the communications data length setting.

Data length	Text data
7 bits	ASCII 20H to 7EH
8 bits	ASCII 20H to 7EH or A1H to FEH

2. Response Codes

Response code	Error name	Cause
"1001"	Command length too long	The command is too long.
"2203"	Operation error	An error occurred in nonvolatile memory.
"0000"	Normal end	Processing was completed normally.

Example:Command: [STX]010000**0801123**[ETX][BCC]Response: [STX]010000**08010000123**[ETX][BCC]

SECTION 4

Functions

This section describes the functions of the G3ZA so that these functions can be used effectively according to the application.

4-1	Changing the Manipulated Variable	24
4-2	Offsetting Control Output ON Timing	25
4-3	Turning OFF the Control Output	25
4-4	Detecting Heater Burnout (4-channel Models Only)	26
4-5	Detecting Heater Overcurrent (4-channel Models Only)	28
4-6	Detecting SSR Short Circuits (4-channel Models Only)	28
4-7	Setting Operation for Errors	30
4-8	Detecting Communications Timeouts.	30

4-1 Changing the Manipulated Variable

The Variable Area Write command is used to change the manipulated variable. The manipulated variable is 0.0% by default when the power supplied is turned ON. This value can be changed to another value by using the Manipulated Variable Save operation command.

Example: The following procedure can be used to change the manipulated variable to 20.0% whenever the power supply is turned ON.

- 1,2,3...**
1. Execute the Variable Area Write command to set the manipulated variable to 20.0% for all channels.
 2. Execute the Manipulated Variable Save operation command.
 3. The manipulated variables will be set to 20.0% the next time power is turned ON.

Using Manipulated Variable Calculations

Manipulated variable calculations can be used to set the control variable for one change based on the manipulated variable for another channel. The following calculation method and set values can be used.

Control variable =

Manipulated variable of source channel x Slope/100.0 + Offset

Set value	Setting
Channels 1 to 8: Source channel	Channel 1 to 8 (Set the channel to use as the source for calculation.)
Channels 1 to 8: Slope	0.0% to 400.0%
Channels 1 to 8: Offset	-400.0% to 400.0%

Note

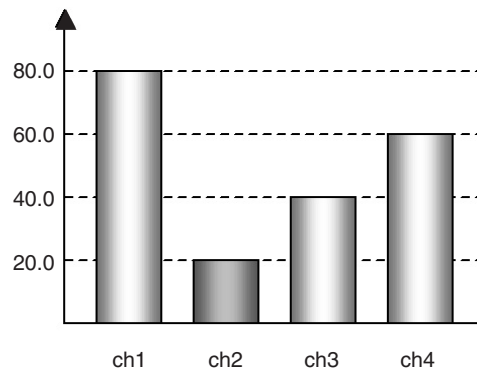
(1) The control variable will be clamped at 0% or 100% if it exceeds the range of 0% to 100%.

(2) The control variable can be read using the Variable Area Read command.

Example:

Channel	1	2	3	4
Manipulated variable	0.0	20.0	0.0	0.0
Source channel	2	2	2	2
Slope	175.0	100.0	125.0	150.0
Offset	15.0	0.0	5.0	10.0
Control variable	50.0	20.0	30.0	40.0

Control variable (%)

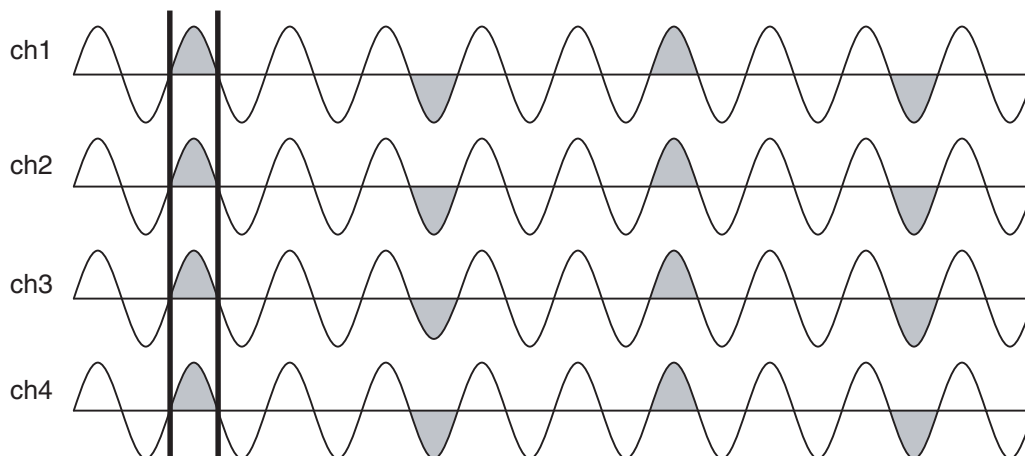


4-2 Offsetting Control Output ON Timing

The ON timing of control outputs for all of the channels can be adjusted to reduce overlapping with each other. Set the Offset Control to perform this. (Offset Control is enabled by default.)

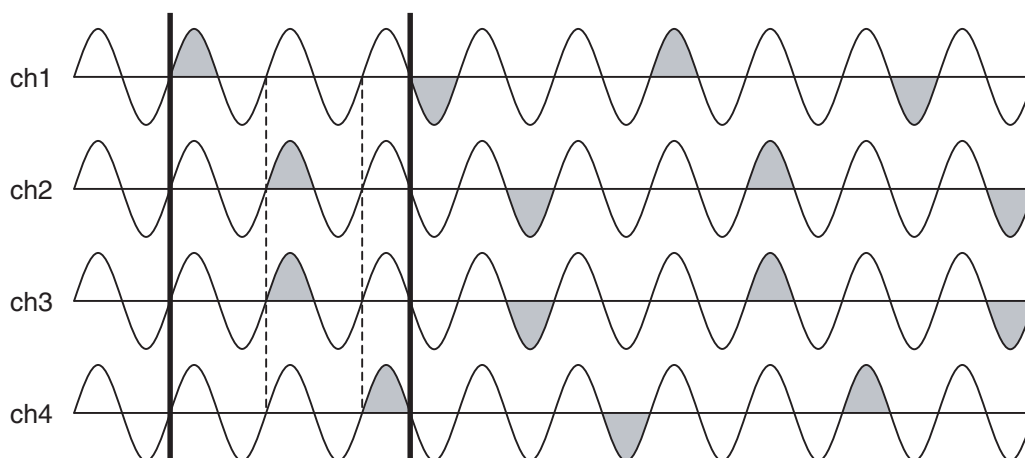
Disabled (No Offset)

In the following diagram, the ON timing overlaps between the channels.



Enabled (Offset)

In the following diagram, overlapping of the ON timing has been reduced.



Note Overlapping will vary with the control variables and changes to the control variables.

4-3 Turning OFF the Control Output

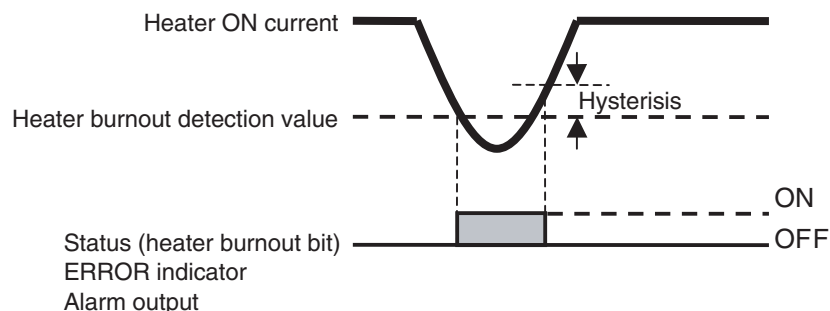
Use the start/stop operation command to turn OFF control outputs. The start/stop command can be used for all channels or for individual channels.

Note The start/stop status is written to nonvolatile memory. If the power is turned OFF when a control output is stopped, it will still be stopped when power is turned back ON. Use the Start/Stop operation command to enable operation again.

4-4 Detecting Heater Burnout (4-channel Models Only)

A heater burnout is detected by determining if the heater current is below the heater burnout detection value when a control output is ON.

Heater Burnout Detection Timing



Set value	Setting range	Default
Channels 1 to 4: Heater burnout detection value	0 to 50 (See note 1.)	0 (disabled)
Hysteresis (See note 2.)	1 to 10	1

Note

- (1) Heater burnouts will not be detected if the detection value is set to 0. Detection status will be forced ON if the detection value is set to 50. Use these to check operation during installation.
- (2) Hysteresis is used to prevent chattering at the detection point. The same hysteresis setting is used for all heater burnout detection, heater overcurrent detection, and SSR short-circuit detection functions.

Operating Conditions

- Turn ON the power supply to the heater either simultaneously with or before the power supply to the G3ZA. False detection will occur if the heater power supply is turned ON after the G3ZA power supply.
- The actual current flowing in the heater may not be the same as the heater's rated current. Check the heater current under actual conditions using the Heater ON Current parameters for channels 1 to 4.
- Keep the total normal heater current to 50 A or less. If 55 A is exceeded, the Heater ON Current parameters for channels 1 to 4 will be 55.
- Detection will be unstable if there is only a small difference between the normal current and burnout current. To achieve stable detection, set the parameters so that there will be a difference of at least 2 A for heaters of less than 10 A and a difference of 3 A or more for heaters of 10 A or more.

Heaters of less than 10 A: Normal current - burnout current ≥ 2 A

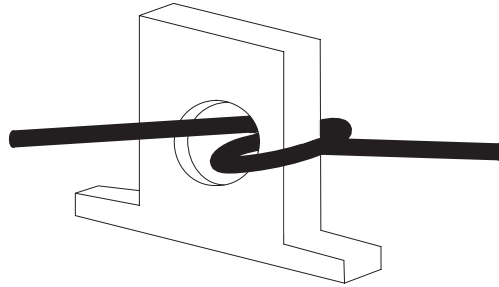
Detection will not be stable if the difference is less than 2 A.

Heaters of 10 A or more: Normal current - burnout current ≥ 3 A

Detection will not be stable if the difference is less than 3 A.

If the conditions for stable detection cannot be met, increase the number of turns of the heater wire through the current transformer. The monitor value for the heater ON current is proportional to the number of turns.

Example:



- Heater burnout detection status can be confirmed by reading the status for individual channels.

Calculating the Detection Current for Heater Burnout

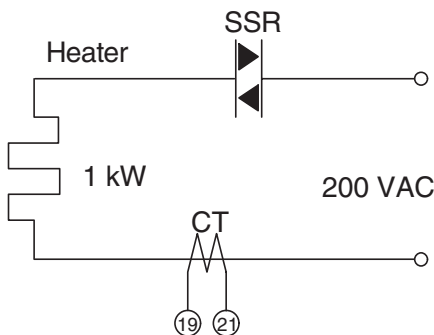
Use the following formula to calculate the detection current.

$$\text{Set value} = \frac{\text{Normal current} + \text{Burnout current}}{2}$$

When two or more heaters are connected through the current transformer, set the detection current to detect burnouts on the heater with the smallest current. If the heater currents are all the same, set the detection current for one wire.

Application Example

Example 1: Using one 1-kW heater (200 VAC)



$$\text{Normal current} = \frac{1000}{200} = 5 \text{ A } (< 10 \text{ A})$$

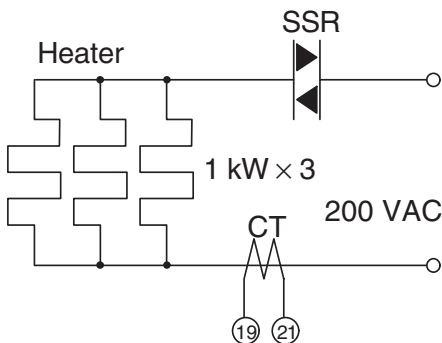
$$\text{Burnout current} = 0 \text{ A}$$

$$\text{Set value} = \frac{5+0}{2} = 2.5 \text{ A} \cong 2 \text{ A}$$

$$(\text{Normal current} - \text{Burnout current} = 5 - 0 = 5 \text{ A } (\geq 2 \text{ A}))$$

The above calculation produces 2.5 A. The minimum setting unit is 1 A, so 2.5 is truncated and 2 A is used.

Example 2: Using three 1-kW heaters (200 VAC)



$$\text{Normal current} = \frac{1000}{200} \times 3 = 15 \text{ A } (\geq 10 \text{ A})$$

$$\text{Current for 1 heater} = \frac{1000}{200} \times 2 = 10 \text{ A}$$

$$\text{Set value} = \frac{15+10}{2} = 12.5 \text{ A} \cong 12 \text{ A}$$

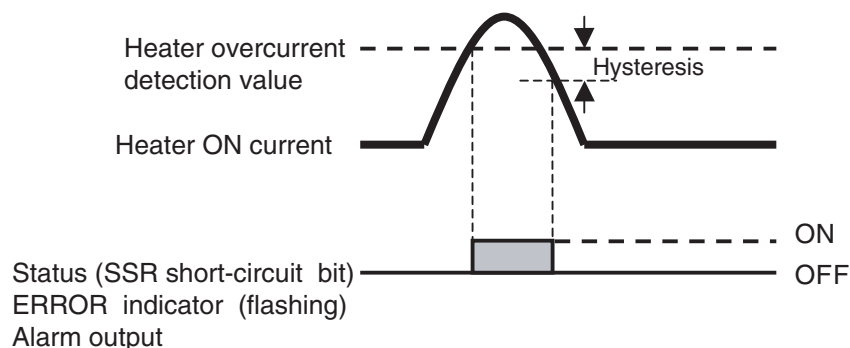
$$(\text{Normal current} - \text{Burnout current} = 15 - 10 = 5 \text{ A } \geq 3 \text{ A})$$

The calculation produces 12.5 A. This is truncated to 12 A, as explained above.

4-5 Detecting Heater Overcurrent (4-channel Models Only)

A heater overcurrent is detected by determining if the heater current is above the heater overcurrent detection value when a control output is ON.

Heater Overcurrent Detection Timing



Set value	Setting range	Default
Channels 1 to 4: Heater overcurrent detection value	0 to 50 (See note 1.)	50 (disabled)
Hysteresis (See note 2.)	1 to 10	1

- Note**
- (1) Heater overcurrents will not be detected if the detection value is set to 50. Detection status will be forced ON if the detection value is set to 0. Use these to check operation during installation.
 - (2) Hysteresis is used to prevent chattering at the detection point. The same hysteresis setting is used for all heater burnout detection, heater overcurrent detection, and SSR short-circuit detection functions.

Operating Conditions

- The actual current flowing in the heater may not be the same as the heater's rated current. Check the heater current under actually conditions using the Heater ON Current parameter for the relevant channel.
- Detection will be unstable if there is only a small difference between the normal current and overcurrent current. To achieve stable detection, set the parameters so that there will be a difference of at least 2 A for heaters of less than 10 A and a difference of 3 A or more for heaters of 10 A or more.
- Heater overcurrent detection status can be confirmed by reading the status for individual channels.

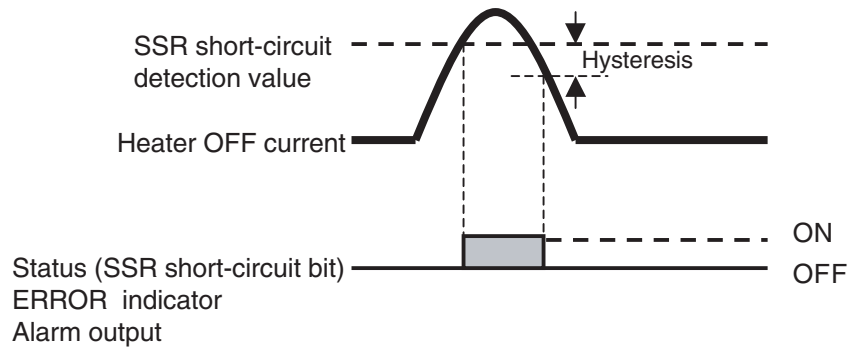
Calculating the Detection Current for Heater Overcurrent

Set the detection current according to the needs of the application.

4-6 Detecting SSR Short Circuits (4-channel Models Only)

An SSR short-circuit is detected by determining if the heater current is above the SSR short-circuit detection value when a control output is OFF.

SSR Short-circuit Detection Timing



Set value	Setting range	Default
Channels 1 to 4: SSR short-circuit detection value	0 to 50 (See note 1.)	50 (disabled)
Hysteresis (See note 2.)	1 to 10	1

Note

- (1) SSR short-circuits will not be detected if the detection value is set to 50. Detection status will be forced ON if the detection value is set to 0. Use these to check operation during installation.
- (2) Hysteresis is used to prevent chattering at the detection point. The same hysteresis setting is used for all heater burnout detection, heater overcurrent detection, and SSR short-circuit detection functions.

Operating Conditions

- The actual current flowing in the heater may not be the same as the heater's rated current. Check the heater current under actual conditions using the Heater OFF Current parameters for channels 1 to 4.
- SSR short-circuit detection status can be confirmed by reading the status for individual channels.

Calculating the Detection Current for SSR Short-circuits

Set the detection current to the value calculated with the following formula or higher.

$$\text{Set value} > \text{Normal leakage current} \times 2$$

4-7 Setting Operation for Errors

The operation to be used when the following errors occur can be set.

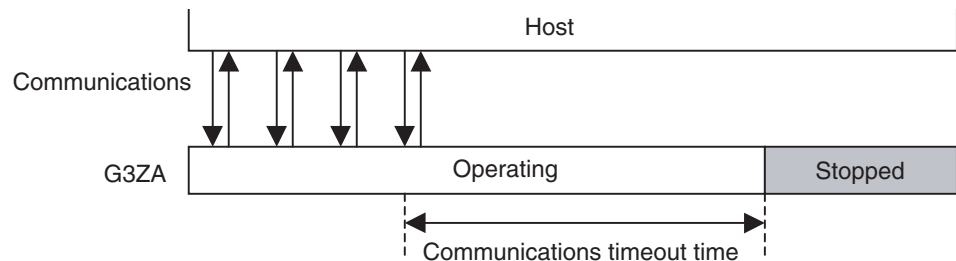
- Zero cross error (See note 2.)
- Heater burnout detection
- Heater overcurrent detection
- SSR short-circuit detection

Operation at error	Operation	Clearing the error
Continue with error clear	Continues.	The error is cleared when normal status is recovered (i.e., the status ERROR indicator and alarm output are turned OFF).
Continue without error clear	Continues.	The error is not cleared even if normal status is recovered. Restore normal status and then use an Operation Command Start operation again.
Stop	Stops for the channel with an error. (See note.)	The error is not cleared even if normal status is recovered and operation will remained stopped. Restore normal status and then use an Operation Command Start operation.

- Note**
- (1) Operation will stop for all channels if a zero cross error occurs.
 - (2) Zero cross error: A zero cross error will occur when there is an error in the load power supply voltage, frequency, or waveform. Refer to *SECTION 5 Troubleshooting* for details.

4-8 Detecting Communications Timeouts

Operation can be stopped if the time when normal communications cannot be performed exceeds the communications timeout time.



Set value	Setting range	Default
Communications timeout time	0 to 60 min	0 (disabled)

- Note**
- (1) Communications timeouts will not be detected if the time is set to 0.
 - (2) The setting is not valid and communications timeout detection will not start until the G3ZA is reset or until the power supply is cycled.

Operation will stop when a communications timeout is detected and the communications error bit in status, the ERROR indicator, and the alarm output will turn ON. Use an Operation Command to clear the error.

SECTION 5

Troubleshooting

This section provides information on problems that may occur during operation and corrective measures for them.

5-1	Errors	32
5-2	Handling Problems	33

5-1 Errors

Error Table

ERROR indicator	Status	Operation	Error	Correction
Lit	No response or an error response	Stops	There is an error in internal memory or in non-volatile memory.	<p>Cycle the power supply.</p> <p>If operation does not recover, use the following procedure, noting that all settings will be returned to their default values.</p> <ul style="list-style-type: none"> • Error Response Received Initialize the settings and perform a software reset with an Operation Command. • Error Response Not Received Set the host data length, stop bits, and parity to the default values for the G3ZA (if a Converter is being used, set it to the same values) and then initialize the settings and perform a software reset with an Operation Command. <p>If operation still does not recover, the G3ZA needs to be repaired.</p>
Lit	Communications error bit is ON.	Stops	A communications timeout has occurred.	<ul style="list-style-type: none"> • Check to see if the communications line is broken. • Check to see if a communications error has occurred. • Check the host to see if it is functioning correctly. • Check the information provided in <i>4-8 Detecting Communications Timeouts</i> on page 30.
Lit	Zero cross error bit is ON.	According to the operation at error setting	A zero cross error has been detected.	<ul style="list-style-type: none"> • Check to see if the load power supply's voltage and frequency are within specifications. The specified ranges are as follows: Controllers with 100 to 240 V Load Voltage: 75 to 264 VAC Controllers with 400 to 480 V Load Voltage: 340 to 528 VAC Frequency (all models) : 47 to 63 Hz • Noise may be a factor. Check the load power supply line for noise and check the general area around the G3ZA for noise.
Lit	Heater burnout bit is ON.	According to the operation at error setting	A heater burnout has been detected.	<ul style="list-style-type: none"> • The heater has burned out. Repair the heater or the heater line. • Check the information provided in <i>4-4 Detecting Heater Burnout (4-channel Models Only)</i> on page 26.
Lit	Heater overcurrent bit is ON.	According to the operation at error setting	A heater overcurrent has been detected.	<ul style="list-style-type: none"> • An overcurrent has occurred to the heater. Return the current to the correct range. • Check the information provided in <i>Wiring Diagrams</i> on page 9 and in <i>4-5 Detecting Heater Overcurrent (4-channel Models Only)</i> on page 28.
Flashing	SSR short-circuit bit is ON.	According to the operation at error setting	An SSR short-circuit has been detected.	<ul style="list-style-type: none"> • The SSR has short-circuited. Replace the SSR. • Check the information provided in <i>Wiring Diagrams</i> on page 9 and in <i>4-6 Detecting SSR Short Circuits (4-channel Models Only)</i> on page 28.

5-2 Handling Problems

Handling Problems

Preliminary Checks

Check item	Items to check
Is the power supply turned ON?	If the power supply is turned ON, the READY indicator will be lit.
Was wiring performed correctly?	Check all of the wiring.
Were settings performed correctly?	<ul style="list-style-type: none"> • Check the switches to see if they are set correctly. • Read out the settings to see if they have been set correctly. • Read out all settings to see if any of them are incorrect.

Handling Problems

Condition	Correction
Communications cannot be performed.	<ul style="list-style-type: none"> • If the SD/RD indicator does not light when communications are attempted, there is a problem with the communications line. Check the wiring of the communications line. • If a communications converter is being used, check the settings of the converter to see if they are correct. • Check the settings of SW1 and SW2 to see if they agree with the settings of the host. • Check the data length, number of stop bits, and parity to see if they are the same as the host. If any of the settings are incorrect or if any are unknown, use the following method for communications. <ol style="list-style-type: none"> 1. Set SW2 to 7. (If more than 16 communications unit numbers are used, set SW2 to F.) 2. Set the baud rate, data length, number of stop bits, and parity of the host to the default values for the G3ZA. If a converter is being used, set the converter to the same values. 3. This should enable communications. Change all settings to the correct values. • Check the communications line to see if it is correct.
Outputs do not turn ON.	<ul style="list-style-type: none"> • Unless the OCC indicator is lit or the control variable is set to 0.0%, then there is a problem in the wiring. Check the wiring of the control outputs. • If the ERROR indicator is lit or flashing, refer to the corrections given in the <i>Error Table</i> on page 32.
Returning settings to default values	<ul style="list-style-type: none"> • Initialize the settings with an Operation Command. All of the settings can be returned to their default values. Refer to the <i>Parameter Tables</i> on page 38 in the <i>Appendix</i> for default values.

Appendix

Specifications

Specifications

Ratings

Control power supply voltage	100 to 240 VAC (50/60 Hz)
Control power supply voltage range	85 to 264 VAC
Power consumption	Approx. 5.9 W
Load power supply voltage	100 to 240 VAC 400 to 480 VAC
Load power supply voltage range	Controllers for 100 to 240 VAC: 75 to 264 VAC Controllers for 400 to 480 VAC: 340 to 528 VAC
Manipulated variable inputs	0.0% to 100.0% (via RS-485 communications)
Current transformer inputs	Single-phase AC, 0 to 50 A
Trigger outputs	One for each channel, 12 VDC $\pm 15\%$, max. load current: 21 mA (with built-in short-circuit protection circuit)
Alarm output	NPN open collector, one output (Max. load voltage: 30 VDC, max. load current: 50 mA, max. residual voltage: 1.5 V, max. leakage current: 1.0 mA)
Indications	LED indicators
Ambient operating temperature	-10 to 55°C (with no icing or condensation)
Ambient operating humidity	25% to 85%
Storage temperature	-25 to 65°C (with no icing or condensation)
Elevation	2,000 m max.
Accessories	Instruction Sheet

Performance

Current accuracy	± 3 A
Insulation resistance	100 M Ω min. (at 500 VDC) between primary and secondary
Dielectric strength	2,000 VAC, 50/60 Hz for 1 min between primary and secondary
Vibration resistance	Vibration frequency: 10 to 55 to 10 Hz, acceleration: 50 m/s ² in X, Y, Z directions
Shock resistance	300 m/s ² three times each in six directions along three axes
Weight of main body	Approx. 200 g (including terminal cover)
Degree of protection	IP20
Memory backup	EEPROM (non-volatile memory), write life: 100,000 writes
Installation environment	Overvoltage category III, pollution degree 2 (according to IEC 60664-1)
Approved standards	UL508 (Listing), CSA22.2 No. 14 EN50178 EN61000-6-4 (EN55011: 1998, A1: 1999 Class A, Group 1) EN61000-6-2: 2001

Model Numbers

Model Numbers

G3ZA-①②③④⑤-⑥-⑦

Number		Code	Specifications
①	No. of control points	4	4 channels
		8	8 channels
②	Control method	None	Ideal cycle control
③	Current transformer input	H	Yes
		A	None
④	Load power supply voltage	2	100 to 240 VAC
		4	400 to 480 VAC
⑤	Communications specifications	03	RS-485
⑥	Communications protocol	FLK	CompoWay/F
⑦	International standards	UTU	Approved by TÜV.

Current Transformer

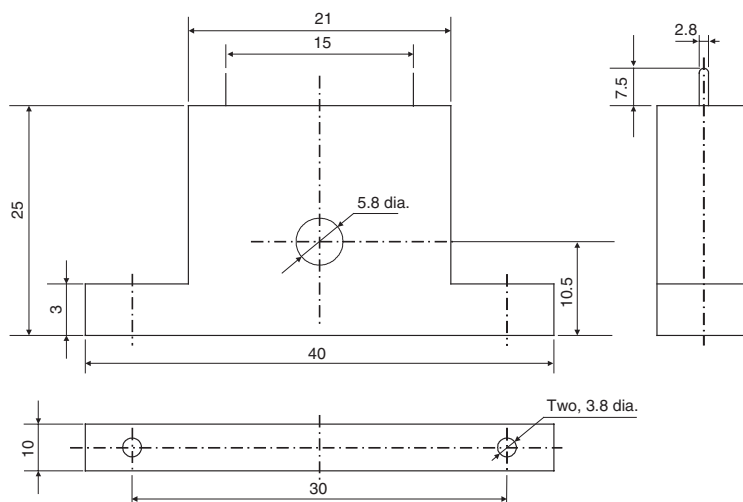
Specifications

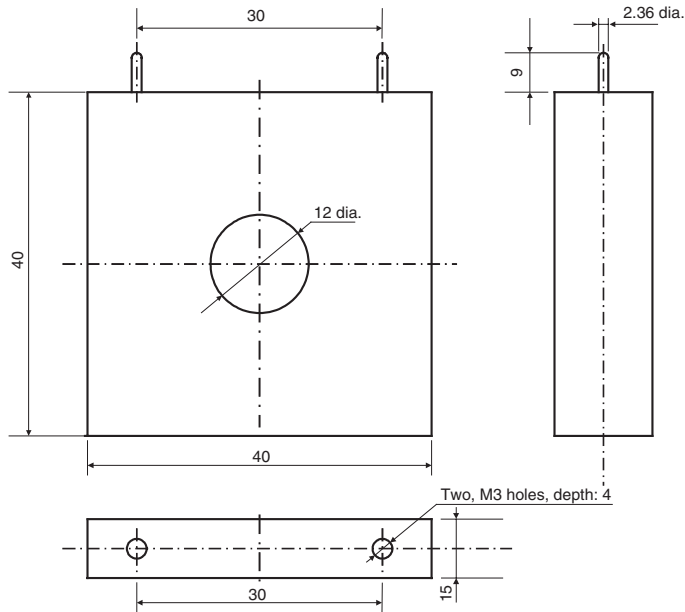
Item	Specification	
Model number	E54-CT1	E54-CT3
Max. continuous heater current	50 A	120 A (See note.)
Dielectric strength	1,000 VAC for 1 min	
Vibration resistance	98 m/s ² , 50 Hz	
Weight	Approx. 11.5 g	Approx. 50 g
Accessories	None	Connection terminals (2) Plugs (2)

Note The maximum continuous current of the G3ZA is 50 A.

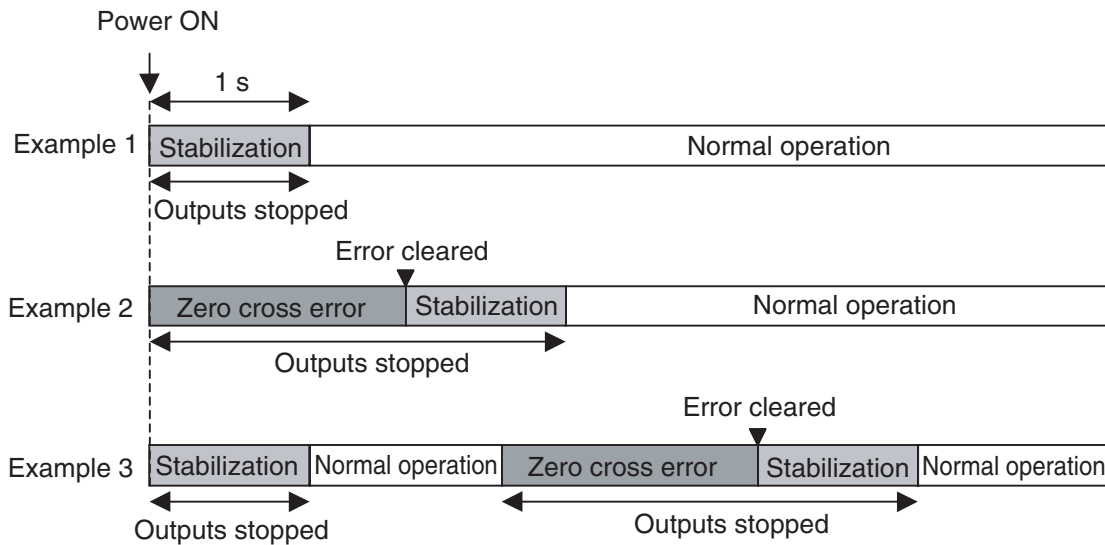
Dimensions (Unit: mm)

E54-CT1



E54-CT3**Startup Operation**

It takes about 1 second for the load power supply to stabilize after the power supply to the G3ZA is turned ON. Outputs will not turn ON during this period. A stabilization period of 1 second is also executed after clearing a zero cross error.



Connecting More Than 16 Controllers

If more than 16 G3ZA Controllers are connected, set SW2 to between 8 and B for the 17th Controller on. The relationship between the settings of SW1 and SW2 is shown in the following table.

kbit/s	sw1 \ sw2	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
9.6	0	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
19.2	1																
38.4	2																
57.6	3																
---	4 to 7																
9.6	8	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
19.2	9																
38.4	A																
57.6	B																
---	C to F																

- Note**
- (1) Up to 31 Controllers can be connected.
 - (2) Do not set SW2 to between 4 and 7 or C and F.
 - (3) It's easiest to set the communications unit number first and then the baud rate.

Setting example: The following settings would be used to set a Controller to communications unit number 7 and a baud rate of 38.4 kbit/s.

SW1 = 7 and SW2 = 2

Parameter Tables

Parameter Tables

Status

Bit	Status	OFF	ON	
31 to 13	Not used.	OFF	---	Operating
12	Start/stop	Operating	Stopped	
11	Not used.	OFF	---	
10	Not used.	OFF	---	Output
9	Alarm output (applies to all channels)	OFF	ON	
8	Control output	OFF	ON	
7	Not used.	OFF	---	Error
6	Not used.	OFF	---	
5	Communications error (applies to all channels)	No	Yes	
4	Zero cross error (applies to all channels)	No	Yes	
3	Not used.	OFF	---	
2	Heater overcurrent	No	Yes	
1	SSR short circuit	No	Yes	
0	Heater burnout	No	Yes	

Example:

Condition	Status
Alarm output and zero cross error bit are ON.	H'00000210
Stopped with no errors	H'00001000

Level	Variable type	Address	Parameter	Setting/monitor range	Default	Unit
Operation	C0 (See note 1.)	0000	Version	---	---	---
		0001	CH1 control variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0002	CH2 control variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0003	CH3 control variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0004	CH4 control variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0005	CH5 control variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0006	CH6 control variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0007	CH7 control variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0008	CH8 control variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0009	CH1 status	---		---
		000A	CH2 status	---		---
		000B	CH3 status	---		---
		000C	CH4 status	---		---
		000D	CH5 status	---		---
		000E	CH6 status	---		---
		000F	CH7 status	---		---
		0010	CH8 status	---		---
		0011	CH1 heater ON current	H'00000000 to H'00000037 (0 to 55)	0	A
		0012	CH2 heater ON current	H'00000000 to H'00000037 (0 to 55)	0	A
		0013	CH3 heater ON current	H'00000000 to H'00000037 (0 to 55)	0	A
		0014	CH4 heater ON current	H'00000000 to H'00000037 (0 to 55)	0	A
		0015	CH1 heater OFF current	H'00000000 to H'00000037 (0 to 55)	0	A
		0016	CH2 heater OFF current	H'00000000 to H'00000037 (0 to 55)	0	A
		0017	CH3 heater OFF current	H'00000000 to H'00000037 (0 to 55)	0	A
		0018	CH4 heater OFF current	H'00000000 to H'00000037 (0 to 55)	0	A
	C1 (See note 1.)	0000	CH1 manipulated variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0001	CH2 manipulated variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0002	CH3 manipulated variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0003	CH4 manipulated variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0004	CH5 manipulated variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0005	CH6 manipulated variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0006	CH7 manipulated variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0007	CH8 manipulated variable	H'00000000 to H'000003E8 (0.0 to 100.0)	0.0	%
		0008	CH1 slope	H'00000000 to H'00000FA0 (0.0 to 400.0)	100.0	%
		0009	CH2 slope	H'00000000 to H'00000FA0 (0.0 to 400.0)	100.0	%

Level	Variable type	Address	Parameter	Setting/monitor range	Default	Unit
Operation	C1 (See note 1.)	000A	CH3 slope	H'00000000 to H'00000FA0 (0.0 to 400.0)	100.0	%
		000B	CH4 slope	H'00000000 to H'00000FA0 (0.0 to 400.0)	100.0	%
		000C	CH5 slope	H'00000000 to H'00000FA0 (0.0 to 400.0)	100.0	%
		000D	CH6 slope	H'00000000 to H'00000FA0 (0.0 to 400.0)	100.0	%
		000E	CH7 slope	H'00000000 to H'00000FA0 (0.0 to 400.0)	100.0	%
		000F	CH8 slope	H'00000000 to H'00000FA0 (0.0 to 400.0)	100.0	%
		0010	CH1 offset	H'FFFFFF060 to H'00000FA0 (–400.0 to 400.0)	0.0	%
		0011	CH2 offset	H'FFFFFF060 to H'00000FA0 (–400.0 to 400.0)	0.0	%
		0012	CH3 offset	H'FFFFFF060 to H'00000FA0 (–400.0 to 400.0)	0.0	%
		0013	CH4 offset	H'FFFFFF060 to H'00000FA0 (–400.0 to 400.0)	0.0	%
		0014	CH5 offset	H'FFFFFF060 to H'00000FA0 (–400.0 to 400.0)	0.0	%
		0015	CH6 offset	H'FFFFFF060 to H'00000FA0 (–400.0 to 400.0)	0.0	%
		0016	CH7 offset	H'FFFFFF060 to H'00000FA0 (–400.0 to 400.0)	0.0	%
		0017	CH8 offset	H'FFFFFF060 to H'00000FA0 (–400.0 to 400.0)	0.0	%
		0018	CH1 source channel	H'00000001 to H'00000008 (1 to 8)	1	---
		0019	CH2 source channel	H'00000001 to H'00000008 (1 to 8)	2	---
		001A	CH3 source channel	H'00000001 to H'00000008 (1 to 8)	3	---
		001B	CH4 source channel	H'00000001 to H'00000008 (1 to 8)	4	---
		001C	CH5 source channel	H'00000001 to H'00000008 (1 to 8)	5	---
		001D	CH6 source channel	H'00000001 to H'00000008 (1 to 8)	6	---
		001E	CH7 source channel	H'00000001 to H'00000008 (1 to 8)	7	---
		001F	CH8 source channel	H'00000001 to H'00000008 (1 to 8)	8	---
		0020	CH1 heater burnout detection value	H'00000000 to H'00000032 (0 to 50)	0	A
		0021	CH2 heater burnout detection value	H'00000000 to H'00000032 (0 to 50)	0	A
		0022	CH3 heater burnout detection value	H'00000000 to H'00000032 (0 to 50)	0	A
		0023	CH4 heater burnout detection value	H'00000000 to H'00000032 (0 to 50)	0	A
		0024	CH1 SSR short-circuit detection value	H'00000000 to H'00000032 (0 to 50)	50	A
		0025	CH2 SSR short-circuit detection value	H'00000000 to H'00000032 (0 to 50)	50	A
		0026	CH3 SSR short-circuit detection value	H'00000000 to H'00000032 (0 to 50)	50	A
		0027	CH4 SSR short-circuit detection value	H'00000000 to H'00000032 (0 to 50)	50	A
		0028	CH1 heater overcurrent detection value	H'00000000 to H'00000032 (0 to 50)	50	A
		0029	CH2 heater overcurrent detection value	H'00000000 to H'00000032 (0 to 50)	50	A
		002A	CH3 heater overcurrent detection value	H'00000000 to H'00000032 (0 to 50)	50	A
		002B	CH4 heater overcurrent detection value	H'00000000 to H'00000032 (0 to 50)	50	A
		002C	Offset control	H'00000000 (Disabled) H'00000001 (Enabled)	Enabled	---

Level	Variable type	Address	Parameter	Setting/monitor range	Default	Unit
Operation	C3 (See note 1.)	0000	Data length (See note 2.)	H'00000000 (7) H'00000001 (8)	7	bits
		0001	Stop bits (See note 2.)	H'00000000 (1) H'00000001 (2)	2	bits
		0002	Parity (See note 2.)	H'00000000 (None) H'00000001 (Even) H'00000002 (Odd)	Even	---
		0003	Send standby time (See note 2.)	H'00000000 to H'00000063 (0 to 99)	20	ms
		0004	Communications time-out time (See note 2.)	H'00000000 (Disabled) H'00000001 to H'0000003C (1 to 60)	0	min
		0005	Operation at error	H'00000000 (Continue with error clear) H'00000001 (Continue with no error clear) H'00000002 (Stop) (See note 3.)	0	---
		0006	Offset value	H'00000000 to H'000003E8 (0.0 to 100.0)	20.0	%
		0007	Hysteresis	H'00000001 to H'0000000A (1 to 10)	1	A

- Note**
- (1) If C in the variable type is changed to 8, 4-digit data can be set or monitored.
 - (2) These settings are valid until the G3ZA is reset or the power is turned ON again.
 - (3) Only the channel with the error will stop.

ASCII Character Table

Upper byte Lower byte	0	1	2	3	4	5	6	7
0	NUL	DLE	SPACE	0	@	P		p
1	SOH	DC1	!	1	A	Q	a	q
2	STX	DC2	"	2	B	R	b	r
3	ETX	DC3	#	3	C	S	c	s
4	EOT	DC4	\$	4	D	T	d	t
5	ENQ	NAK	%	5	E	U	e	u
6	ACK	SYN	&	6	F	V	f	v
7	BEL	ETB	'	7	G	W	g	w
8	BS	CAN	(8	H	X	h	x
9	HT	EM)	9	I	Y	i	y
A	LF	SUB	*	:	J	Z	j	z
B	VT	ESC	+	;	K	[k	{
C	FF	FS	,	<	L	\	l	
D	CR	GS	-	=	M]	m	}
E	SO	RS	.	>	N	^	n	~
F	SI	US	/	?	O	_	o	DEL

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Revision History

A manual revision code appears as a suffix to the catalog number on the front cover of the manual.

Cat. No. Z200-E1-01



Revision code

The following table outlines the changes made to the manual during each revision. Page numbers refer to the previous version.

Revision code	Date	Revised content
01	April 2004	Original production

Revision History

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 - Shipments shall be by a carrier selected by Omron; Omron will not drop ship except in "break down" situations.
 - Such carrier shall act as the agent of Buyer and delivery to such carrier shall constitute delivery to Buyer;
 - All sales and shipments of Products shall be FOB shipping point (unless otherwise stated in writing by Omron), at which point title and risk of loss shall pass from Omron to Buyer; provided that Omron shall retain a security interest in the Products until the full purchase price is paid;
 - Delivery and shipping dates are estimates only; and
 - Omron will package Products as it deems proper for protection against normal handling and extra charges apply to special conditions.
- Claims.** Any claim by Buyer against Omron for shortage or damage to the Products occurring before delivery to the carrier must be presented in writing to Omron within 30 days of receipt of shipment and include the original transportation bill signed by the carrier noting that the carrier received the Products from Omron in the condition claimed.
- Warranties.** (a) **Exclusive Warranty.** Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed in writing by Omron). Omron disclaims all other warranties, express or implied. (b) **Limitations.** OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, ABOUT NON-INFRINGEMENT, MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OF THE PRODUCTS. BUYER ACKNOWLEDGES THAT IT ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. Omron further disclaims all warranties and responsibility of any type for claims or expenses based on infringement by the Products or otherwise of any intellectual property right. (c) **Buyer Remedy.** Omron's sole obligation hereunder shall be, at Omron's election, to (i) replace (in the form originally shipped with Buyer responsible for labor charges for removal or replacement thereof) the non-complying Product, (ii) repair the non-complying Product, or (iii) repay or credit Buyer an amount equal to the purchase price of the non-complying Product; provided that in no event shall Omron be responsible for warranty, repair, indemnity or any other claims or expenses regarding the Products unless Omron's analysis confirms that the Products were properly handled, stored, installed and maintained and not subject to contamination, abuse, misuse or inappropriate modification. Return of any Products by Buyer must be approved in writing by Omron before shipment. Omron Companies shall not be liable for the suitability or unsuitability or the results from the use of Products in combination with any electrical or electronic components, circuits, system assemblies or any other materials or substances or environments. Any advice, recommendations or information given orally or in writing, are not to be construed as an amendment or addition to the above warranty. See <http://oeweb.omron.com> or contact your Omron representative for published information.
- Limitation on Liability; Etc.** OMRON COMPANIES SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED IN CONTRACT, WARRANTY, NEGLIGENCE OR STRICT LIABILITY. Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.
- Indemnities.** Buyer shall indemnify and hold harmless Omron Companies and their employees from and against all liabilities, losses, claims, costs and expenses (including attorney's fees and expenses) related to any claim, investigation, litigation or proceeding (whether or not Omron is a party) which arises or is alleged to arise from Buyer's acts or omissions under these Terms or in any way with respect to the Products. Without limiting the foregoing, Buyer (at its own expense) shall indemnify and hold harmless Omron and defend or settle any action brought against such Companies to the extent based on a claim that any Product made to Buyer specifications infringed intellectual property rights of another party.
- Property; Confidentiality.** Any intellectual property in the Products is the exclusive property of Omron Companies and Buyer shall not attempt to duplicate it in any way without the written permission of Omron. Notwithstanding any charges to Buyer for engineering or tooling, all engineering and tooling shall remain the exclusive property of Omron. All information and materials supplied by Omron to Buyer relating to the Products are confidential and proprietary, and Buyer shall limit distribution thereof to its trusted employees and strictly prevent disclosure to any third party.
- Export Controls.** Buyer shall comply with all applicable laws, regulations and licenses regarding (i) export of products or information; (ii) sale of products to "forbidden" or other proscribed persons; and (iii) disclosure to non-citizens of regulated technology or information.
- Miscellaneous.** (a) **Waiver.** No failure or delay by Omron in exercising any right and no course of dealing between Buyer and Omron shall operate as a waiver of rights by Omron. (b) **Assignment.** Buyer may not assign its rights hereunder without Omron's written consent. (c) **Law.** These Terms are governed by the law of the jurisdiction of the home office of the Omron company from which Buyer is purchasing the Products (without regard to conflict of law principles). (d) **Amendment.** These Terms constitute the entire agreement between Buyer and Omron relating to the Products, and no provision may be changed or waived unless in writing signed by the parties. (e) **Severability.** If any provision hereof is rendered ineffective or invalid, such provision shall not invalidate any other provision. (f) **Setoff.** Buyer shall have no right to set off any amounts against the amount owing in respect of this invoice. (g) **Definitions.** As used herein, "including" means "including without limitation"; and "Omron Companies" (or similar words) mean Omron Corporation and any direct or indirect subsidiary or affiliate thereof.

Certain Precautions on Specifications and Use

- Suitability of Use.** Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases but the following is a non-exhaustive list of applications for which particular attention must be given:
 - Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this document.
 - Use in consumer products or any use in significant quantities.
 - Energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
 - Systems, machines and equipment that could present a risk to life or property. Please know and observe all prohibitions of use applicable to this Product.
 NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY OR IN LARGE QUANTITIES WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON'S PRODUCT IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.
- Programmable Products.** Omron Companies shall not be responsible for the user's programming of a programmable Product, or any consequence thereof.
- Performance Data.** Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability.
- Change in Specifications.** Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.
- Errors and Omissions.** Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical or proofreading errors or omissions.



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